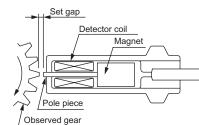
# MS Series MS Magnetic Pickup

MS Series Magnetic Pickup mounted near the observed gear outputs a frequency signal (detected frequency) proportional to the rotating speed of rotating machinery.

It is most suitable for controlling the number of revolutions and also for detecting overspeed of rotating machinery. M16 and M24 mounting threads as well as integral cable type and cable connector type are available.





## Specifications

| Model Code No.              | MS-1601  | MS-1602  | MS-2401  | MS-2402  |
|-----------------------------|--|--|--|--|
| DC Resistance               | 95 to 115Ω at 25°C (77°F)  |  | 220 to 260Ω at 25°C (77°F)   |  |
| Inductance                  | 35mH (typ.)  |  | 115mH (typ.)   |  |
| Observed gear type          | involute gear Module 1 to 4  |  | involute gear Module 3 to 10   |  |
| Operating temperature range | -10 to +120°C (14 to 248°F)  |  |  |  |
| Vibration resistance        | 196m/s <sup>2</sup> (20g REF.)   |  |  |  |
| Threaded size               | M16×1  |  | M24×1.5  |  |
| Cable or connector          | With integral cab<br>(With 2m Teflon <sup>®</sup> 2-wire twisted<br>pair shielded cable) | With connector <sup>*1</sup><br>MS3102E10SL-3P<br>MS3108E10SL-3S | With integral cable<br>(with 2m Teflon <sup>®</sup> 2-wire twisted<br>pair shielded cable) | With connector <sup>*1</sup><br>MS3102E10SL-3P<br>MS3108E10SL-3S |
| Mass                        | Approx. 160g   | Approx. 110g   | Approx. 380g   | Approx. 300g   |

\*1. The upper side is a socket connector and the lower side is for an L-shaped plug. Teflon<sup>®</sup> is a Registered Trademark of E.I.DuPont Co.

### Gear material

It should be a high permeability magnetic material(SS400 is recommended).

#### Output voltage characteristics (load resistance 10kΩ)

$$f = \frac{\mathbf{Rz}}{60}$$

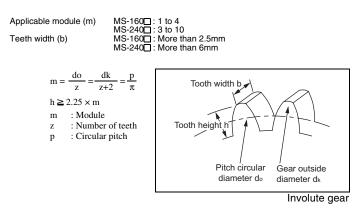
$$f : Detected frequency$$

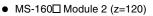
$$\mathbf{R} : Number of revolution (RPM)$$

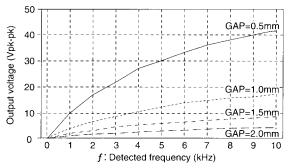
$$\mathbf{z} : Number of teeth$$

Gear shape Involute gears are most suitable. Gears with large modules or different

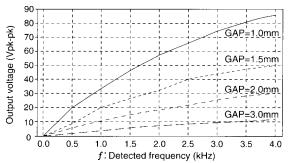
shapes may cause large waveform distortion that prevents accurate detection. If the rotating shaft moves in the axial direction, take care that the pole center is not dislocated from the gear.



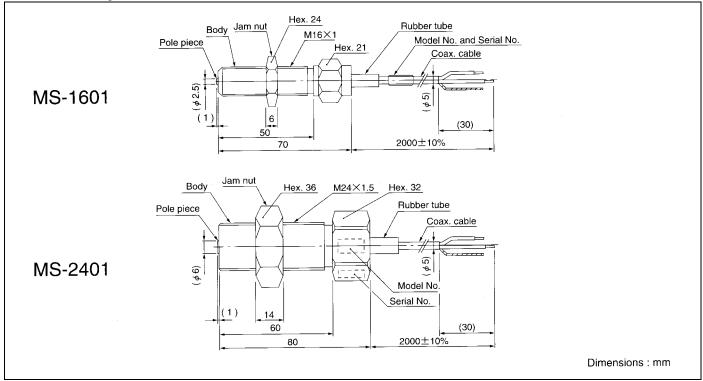












## Outline Drawing MS-1602 MS-2402

